

IN THE SPECIFICATION:

Change the title to read:

METHOD AND DEVICE FOR REMOVING CUTTINGS FROM A SUBSEA
BOREHOLE

Page 1, line 2, insert:

Background of the Invention

delete line 6;

line 21:

~~Prior Art Technology~~ Description of Related Art

Page 2, line 12:

~~Objectives~~ Summary of the Invention

delete lines 17-19.

Page 3, line 8:

~~The invention in more detail~~ Brief Description of the

Drawings

before line 15
~~line 16~~, insert:

Description of the Preferred Embodiments

CF 5/25/10

IN THE SPECIFICATION:

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Page 3, ^{after line 14} ~~between lines 13 and 14~~, insert:

Figure 6 is an enlarged perspective view of a coupling between an connector hose and an ejector according to the invention.

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Page 3, line ³⁵ ~~31~~ page 4, line 9:

The assembly 1 of ROV 2/ pump 3/connecting hose 4 may easily be connected to and disconnected from the ejector 5 as desired, by the coupling 11. This way the ROV may also be used for other purposes. Furthermore the suction hose 6 may be adapted for connection to the borehole 7 with another coupling 12. It is preferable that the couplings 11 and 12 are of such a type that they may be operated by an ROV, preferably the ROV to which they are to be connected. Typically the coupling 11 will be of a type commonly referred to as a rapid coupling. The construction of the coupling 11 as such is not important, though it will generally comprise a locking member that on a short rotating movement or a simple axial movement provides for a sealed locking of the coupling parts 11a and 11b to each other. The locking member will typically be operable by the common, external manipulators arranged on an ROV. The second coupling 12 may be of the same type as coupling 11 or of another type.

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Page 6, ^{after line 2} ~~between lines 2 and 3~~, insert:

Figure 6 shows an enlargement of the coupling between the connecting hose 4 and the ejector 5. The coupling is a quick connect coupling as is well known in the art, including a male portion 11a and a female portion 11b, easily connected and disconnected by an ROV by simple axial or radial movement.